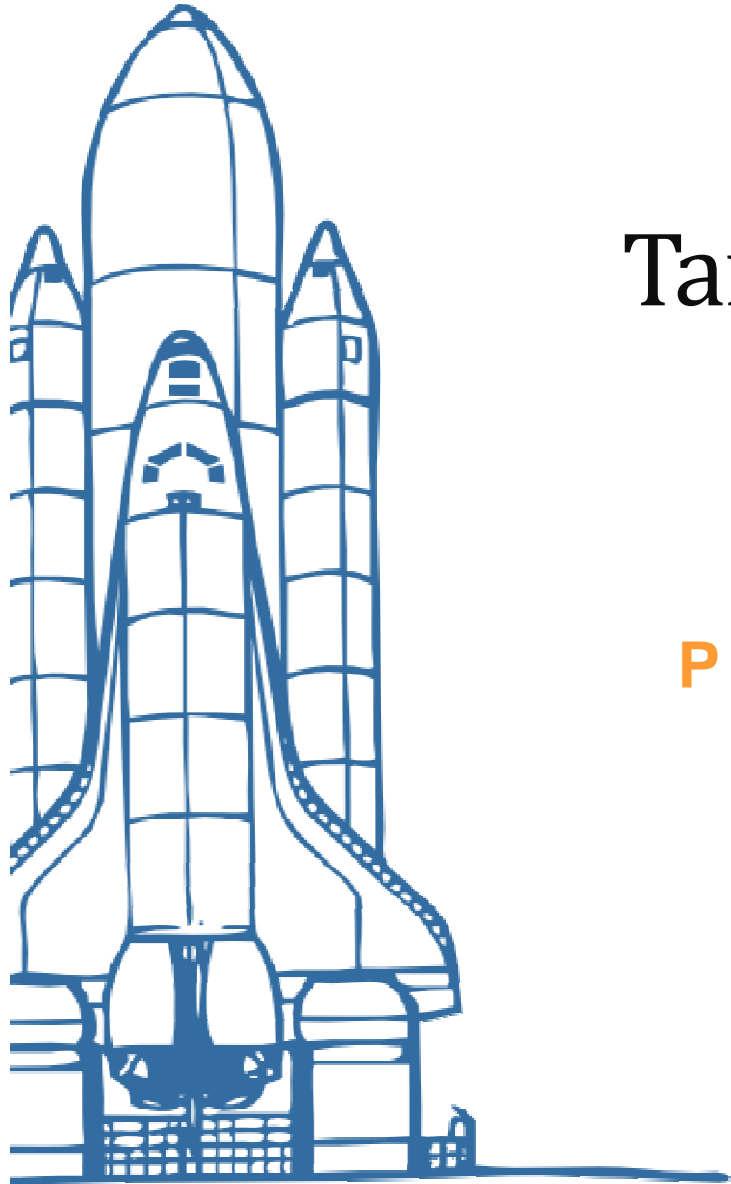


December 20, 2011



Target Tracking by Using Seismic Sensor

PROJECT PRESENTATION

spaceShuttle

Sponsored by **aselsan**



Outline

- About Team
- Seismic Sensors
- Problem Definition
- Motivation and Goal
- Our Solution
 - Features of the project
 - Components of the project
- Up to now what we did
- Future Work

Our Team - *spaceShuttle*

- Mustafa MIZRAK
- Anıl ERKOÇ
- Hüseyin ÜNAL
- Ali Fatih GÜNDÜZ

Seismic Sensor

- Detects vibrations occurred on the ground
- Very sensitive to 25 meters
- Used to monitor protected areas;
to stop immigration,
to secure border lines,
to protect gas and petroleum energy stations.



Seismic Sensors Are Used at

- Power Stations
- International Borders
- Nuclear Power Plants
- Embassies
- Gas and Petroleum Pipelines
- Research Establishments



Seismic Sensors

- Real time reaction from information acquisition to field operations
 - ❖ US Border Patrol
 - ❖ British Petroleum
 - ❖ NATO
 - ❖ Australian Attorney General's Office
 - ❖ Duke Energy
 - ❖ Egypt LNG





Well...

What is the condition in our country?

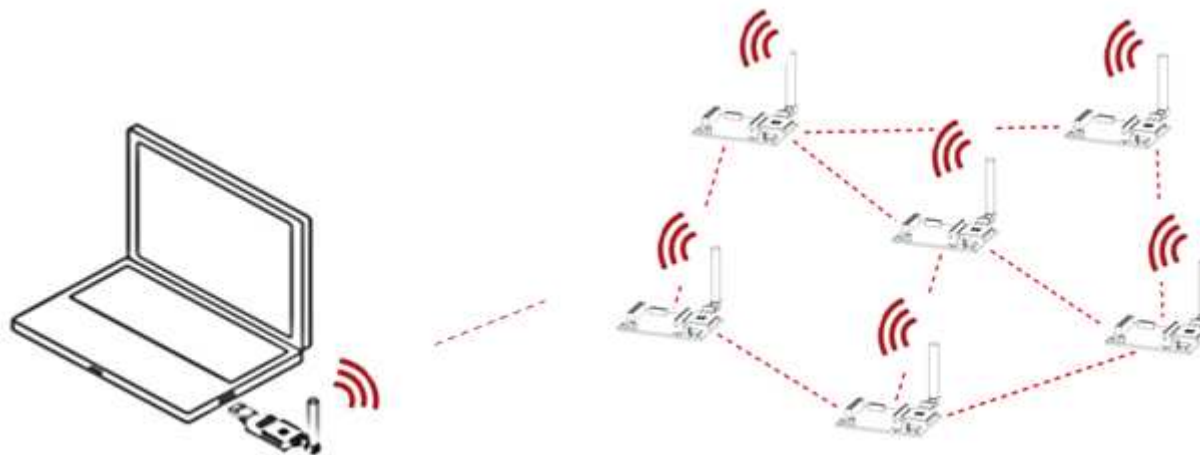


Problem Definition

- Border crossing of refugee and terrorists
- Cost of monitoring border lines from guard stations
- Terrorist raids to the border military guard stations

About the project

Real time object tracking by analyzing waves of seismic sensors object generates while it moves over the ground



*Sensors are
previously
deployed*

Our task in this project

- We will work on sensor part of this huge project
- Sensor part of this project contains three subparts
 - Detection
 - Deployment
 - Target Tracking

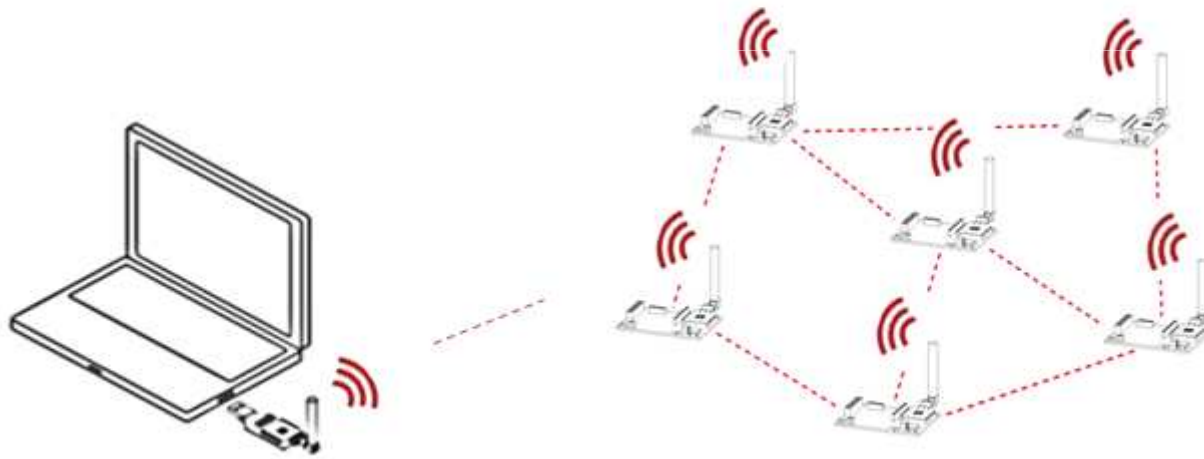
We will work on target tracking by seismic sensors.

Our Goal

- Implementing a target tracking algorithm
- Implementing a Geographic Information System (GIS) based System Simulator:
 - Manually accepts sensor position and target route
 - Shows present sensors on the map
 - Calculates route of targets using the sensor inputs and show them on the map
- Evaluating the performance of the algorithm with the originally entered route (minimizing error margin)

Features of the project

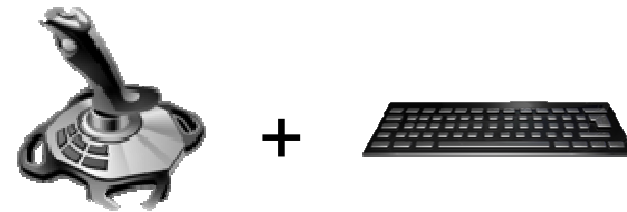
- Getting signals from seismic sensors previously deployed



Features of the project

- Or manually accepting route with

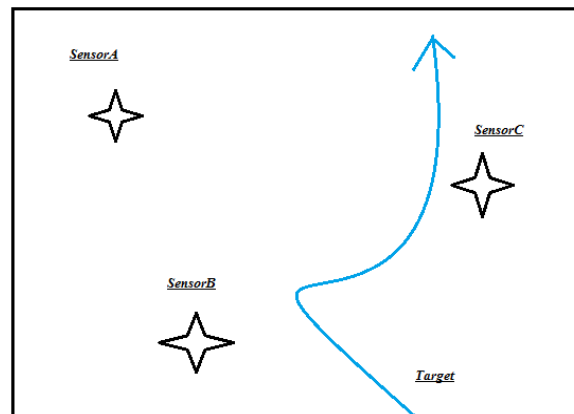
- Keyboard and
- Joystick



- Adding sensors manually to the map

Features of the project

- Determining route of targets via Target Tracking Algorithm (extending and optimizing Kalman Filter approach)
- Reducing noise margin



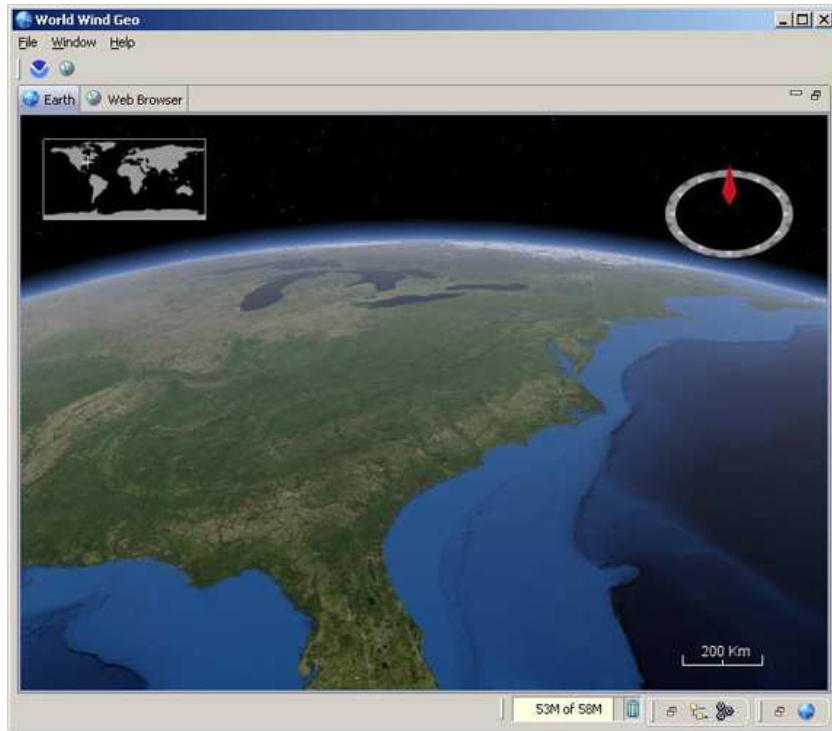
- Showing routes and sensors on the real 3D map (NASA World Wind API will be used)



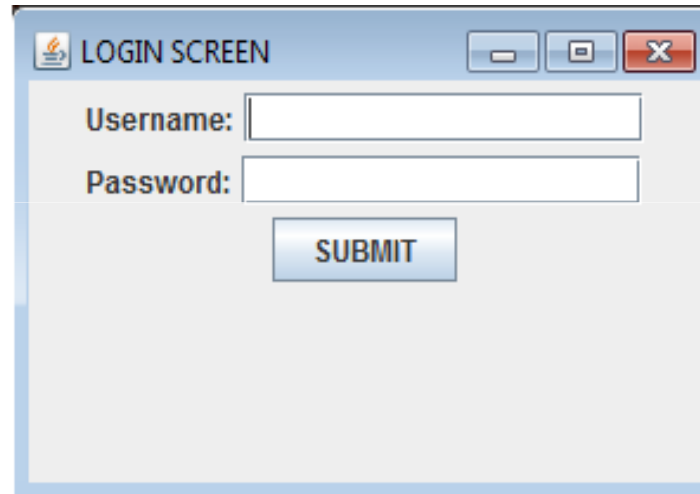
NASA World Wind API

- An open source virtual globe developed by NASA
- Shows meteorological events on world map
- Provides opportunity to develop demo applications on World map

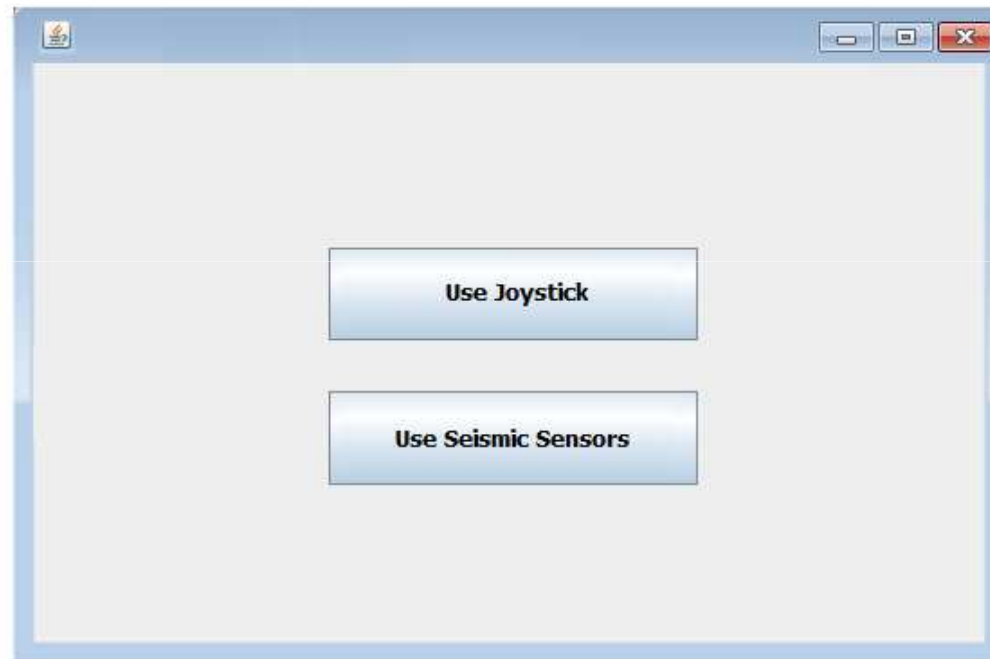
NASA World Wind Snapshots



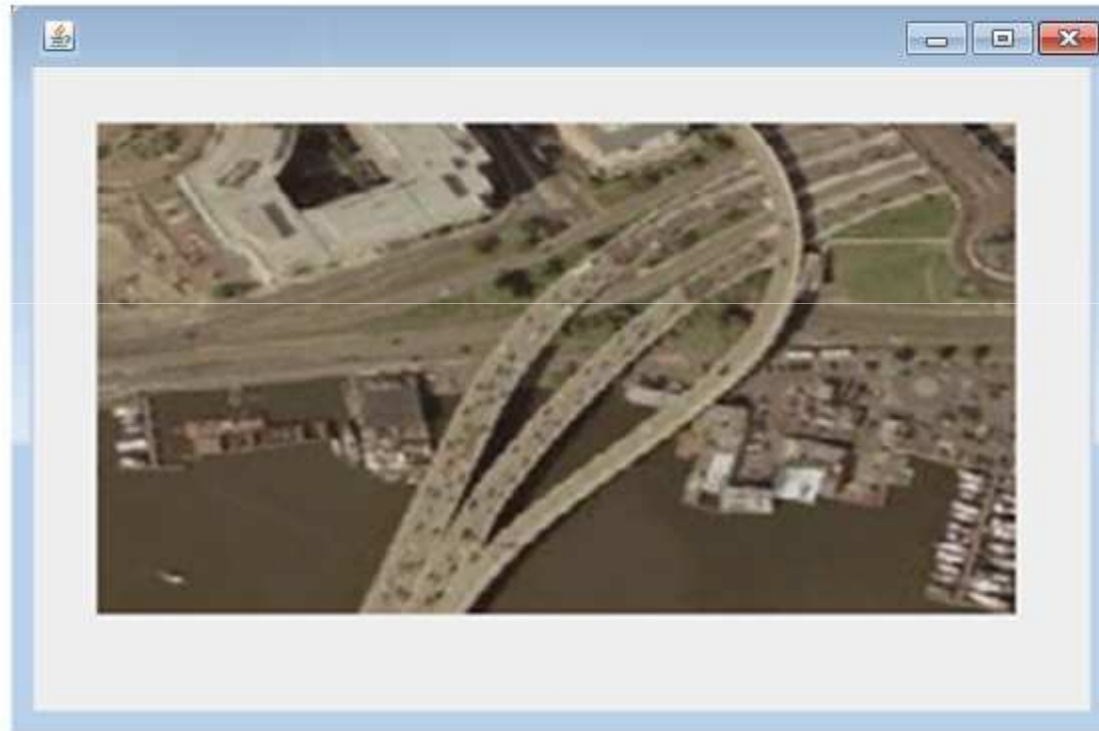
Snapshots of GUI



Snapshots



Snapshots



Future Work

- Designing and implementing efficient, reduced noise margin Kalman Filter algorithm (extended Kalman Filter)
- Implementing a GUI containing real 3D World map, seismic sensors and joystick

References

- <http://www.ibm.com/developerworks/rational/library/content/RationalEdge/sep04/bell/>
- <http://www.agilemodeling.com/artifacts/classDiagram.htm>
- <http://gislounge.com/geodatabases-explored-vector-and-raster-data/>

Questions ?





Thank you...