## **Sprint Retrospective Document**

Date: 06/11/2017

Group name / Project name: 12 /Collaborator

Members: Cansın Canberi, M. Raşit Özdemir, Tahsincan Köse, Burak Hocaoğlu

Assistant: Güneş Sucu Supervisor: Erol Şahin

## Sprint 2 plan

Item ID	ID of the related workpackage (from the Kick-off doc)	Description	Status
1	2	Motion Planning in collision-free workspace.	New
2	3	Shared area will be recognized by the robotic arm.	New
3	2	Motion Planning in static collision-rich workspace	New

## Overall progress

	Spri nt 1	Spri nt 2	Spri nt 3	Spri nt 4	Sprin t 5
MF 1	25%				
MF 2	0%				
MF 3	0%				
MF 4	15%				
MF 5	0%				
MF 6	0%				
MF 7	0%				

MF 8	0%		
MF 9	0%		
MF 10	0%		
MF 11	0%		
MF 12	0%		
MF 13	0%		
MF 14	0%		

This section will be filled in by your supervisor.

Please grade the items below using the following scale:

- 1=Poor
- 2=Minimal
- 3=Sufficient
- 4=Above Average
- 5=Excellent

Criteria	Grade		
Progress of the team in this sprint. (Grade percentage: 50%)			
The accuracy of the summary table above (e.g. are the task status declarations correct?).  (Grade percentage: 25%)			
Considering the weekly meetings, the attendance and preparation level of the team (i.e. Toplantılara düzenli olarak ve hazır bir şekilde, örneğin bir toplantı gündemi oluşturarak, katıldılar mı?) (Grade percentage: 25%)			