

Sprint Retrospective Document

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Project acronym: ROBOCON-OCU

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Sprint 2 summary

Item ID	WP ID	Status	Group's comments
1	2	In progress	Most of the peripherals are chosen but for final decision, we need to finalize our electromechanical design.
2	3	Complete	Minor issues still exist.
3	4	In progress	General structure of the message types are created, finalization of these message types will be done in the next sprint.
4	5	Complete	
-	9	Was not on the initial plan (Complete)	Selection of the GUI framework that will be used in the operator system is done.

Sprint 3 plan

Item ID	WP ID	Description	Status
1	4	Design and implementation of message types representing robot state and control signals for wireless communication	Leftover from Sprint 2
2	9	Implementation of a simple GUI application with video streaming capability	New
3	5	Transmission of HD video between two subsystems in soft real time	New
4	4	Establishing a robust communication between operator and on-board system	New

Overall progress

	Sprint 1	Sprint 2	Sprint 3	Sprint 4	Sprint 5
MF1	5%	12%			
MF2	5%	9%			
MF3	0%	17%			
MF4	0%	19%			
MF5	0%	0%			
MF6	0%	5%			
MF7	0%	5%			
MF8	0%	10%			
MF9	0%	0%			
MF10	0%	0%			