

Sprint Retrospective Document

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Project acronym: ROBOCON-OCU

Members: Zeynep Sonat Baltacı, Cenk Cidecio, Furkan Davulcu, İrem Meltem Özil

Supervisor: Uluç Saranlı

Sprint 9 summary

Item ID	WP ID	Status	Group's Comments
1	9	Not started	
2	8	Not started	
3	8	In progress	A simple design with buttons, sliders, knobs on the sides and the 10 inch touch screen in between them will be the basis of the final design.
4	7	Complete	
5	6	Complete	
6	10	Complete	
7	7	In progress	A working example with MiniRHex robot has done but API still needs a little work to be finalized.
8	5	Complete	
9	9	In progress	The input that received from MCU is not connected to the other components. The other components communicate well.
10	3	Not started	
11	10	In progress	The initial tests are began with further development, more tests will be done.

The plan until the CENG Demo Day

ID	Job Description
1	Build the physical operator system
2	Testing and integration of the system components
3	Create multiple operation modes for robots(MiniRHex and possibly another robot platform called Turtle Rover)
4	Fix the serial communication problem between on-board system and the microcontroller unit of the MiniRHex

Overall progress

[illegible]